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# Model Parameter Identification Based on Hybrid Metaheuristic Algorithms

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#### Abstract

In this paper, Ant Lion Optimizer (ALO) has been hybridized with Genetic Algorithm (GA) for a model parameter identification problem. When dealing with real-world and large-scale problems, it becomes evident that concentrating on a sole metaheuristic algorithm is rather restrictive. A skilled combination between metaheuristics or other optimization techniques, a so called hybrid metaheuristic, can provide more efficient behaviour and higher flexibility. Hybrid metaheuristics combine the advantages of one algorithm with the strengths of another.

#### **Numerical results**

The proposed ALO-GA hybrid algorithm has been applied to estimate parameters of an *E. coli* cultivation process model. A series of 30 runs has been conducted due to the stochastic characteristics of the applied algorithm. The average, the best and the worst results of these 30 runs for the criteria value J (Table 1) and the model parameters (Table 2) have been observed in order to compare the results of the model parameters' identification. The standard deviation (SD) of the estimates has been also evaluated.

ALO, based on the interaction between antlions and ants in a trap, and GA, based on the mechanics of the nature selection, are two efficient biologically inspired population-based algorithms. To demonstrate the effectiveness of ALO-GA for a real-world problem, parameter identification of an *Escherichia coli* MC4110 fedbatch cultivation process model has been considered. The computational results of the designed algorithm have been compared to the results of various hybridized biologically inspired techniques applied to the same problem. The results clearly show that the proposed algorithm ALO-GA outperforms the considered algorithms.

#### Hybrid Ant Lion Optimizer-Genetic Algorithm

ALO is a novel metaheuristic swarm-based approach [1] introduced to emulate the hunting behavior of ant lions in nature. This behavior is described by five important phases of hunting ants: random walk, building a trap, trapping ants, sliding the ants towards the antlion, catching the prey and rebuilding the trap.

GA was developed to model adaptation processes using a recombination operator with mutation as a background operator [2]. GA maintains a population of individuals. Each individual represents a potential solution to the problem in consideration. Each solution is evaluated and a new population is formed by selecting more fit individuals. The proposed hybrid algorithm, named ALO-GA, has been designed to improve both the exploration and exploitation and thus to present a powerful and efficient algorithm for real-world numerical optimization problems. As a result, the speed and the precision of the algorithm's convergence are also improved. The pseudo code of the ALO-GA is as follows:

#### begin

Define the input parameters for both ALO and GA

% Start ALO

*Initialize the first population of ants and antlions randomly* 

*Calculate the fitness of ants and antlions* 

Find the best antlion and adopt it as the elite (determined optimum)

**for** j := 1 to size of initial population  $Pop_0$ 

while the end criterion is not satisfied

*for* each ant

The results (both average and the best), presented in Tables 1 and 2, show that the ALO-GA hybrid algorithm finds the solution with the highest quality, e.g. the smallest objective function value (J = 4.3610). The next best result is achieved by the GA-ACO hybrid algorithm (J = 4.3803).

The model predictions for the biomass and the glucose concentrations, based on the hybrid algorithms estimated sets of model parameters, are compared to the experimental data points of the considered *E. coli* fed-batch cultivation process in Fig. 1 and Fig. 2.

Table 1. Comparison of the objective function values obtained by ALO with published ones [3, 4]

Algorithm	J					
	average	best	worst	SD		
ACO-GA	4.5765	4.4903	4.6865	0.06916		
GA-ACO	4.5706	4.3803	4.6949	0.06325		
ACO-FA	4.5196	4.4013	4.6803	0.05914		
ALO-GA	4.4752	4.3610	4.6617	0.04967		

#### Table 2. Comparison of the parameter estimates obtained by ALO with the published ones [3, 4]

Algorithm	Model parameters						
	$\mu_{\max}$	SD	$k_{_S}$	SD	$Y_{S/X}$	SD	
ACO-GA	0.4976	0.0120	0.0135	0.0023	2.0221	0.0025	
GA-ACO	0.4946	0.0121	0.0123	0.0020	2.0204	0.0024	
ACO-FA	0.4824	0.0110	0.0114	0.0019	2.0206	0.0021	
ALO-GA	0.5022	0.0124	0.0146	0.0024	2.0182	0.0020	

Select an antlion using Roulette wheel

Update the parameters of the random walk

Create a random walk and normalize it

Update the position of the ant

### end for

Calculate the fitness of all ants

Replace an antlion with its corresponding ant if it becomes fitter

Update the elite if an antlion becomes fitter

#### end while

Memorize the best solution for the current iteration in  $Pop_0$ 

#### end for

#### % Start GA

Set the initial population  $Pop_0$  to the set of best solutions generated by ALO

Calculate the value of the fitness function for each individual in  $Pop_{0}$ 

#### for i := 1 to MaxGeneration

Select individuals  $Pop_i$  from the current population  $Pop_{i-1}$  in a way that gives advantage to better individuals.

Perform crossover with probability p<sub>c</sub>

Perform mutation with probability  $p_m$ 

Calculate the value of the fitness function for each individual in Pop<sub>i</sub>

#### end for

Rank the solutions, find the current best and memorize

#### end begin



### Fig. 1 Time profiles of the process variable biomass: real experimental data and model predicted data





#### **Mathematical model**

The application of the general state space dynamical model to the fed-batch cultivation process of bacteria *E. coli* leads to the following nonlinear differential equation system:



- X the concentration of the biomass, [g/L],
  - S the concentration of the substrate (glucose), [g/L];
  - F the feeding rate, [L/h];
  - V- the volume of the bioreactor, [L];
  - Sin the initial glucose concentration in the feeding solution, [g/L];  $\mu$  – the specific growth rate described by Monod kinetics, [1/h];
  - $\mu_{max}$  the maximum growth rate, [1/h];
- $k_s$  a saturation constant, [g/L];
- Y<sub>s/x</sub> an yield coefficient, [-].



#### Time, [h] Time, [h]

### Fig. 2. Time profiles of the process variable substrate: real experimental data and model predicted data

#### References

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